

#### RY8601 Features

- Wide 4.5V to 60V Operating Input Range
- 0.6A Continuous Output Current
- 500KHz Switching Frequency
- Short-Circuit Protection
- Built-in Over Current Limit
- Built-in Over Voltage Protection
- PSM Mode for High Efficiency in Light Load

- 500mΩ Internal Power MOSFETs
- Output Adjustable from 0.8V
- Low EMI Signature
- Internal Soft-Start
- Thermal Shutdown
- Available in SOT23-6 Packages
- -40°C to +85°C Temperature Range

### **RY8601 Applications**

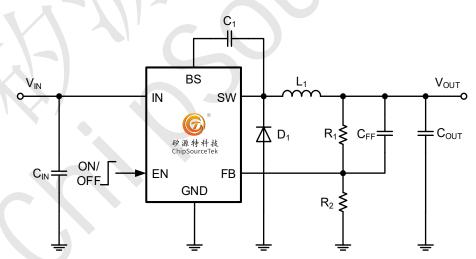
- Automotive GPS
- Automotive Entertainment

- Power Supply for Linear Chargers
- Network Equipment

## **RY8601 General Description**

The RY8601 is a current mode monolithic buck switching regulator. Operating with an input range of 4.5V~60V, it supplies 0.6A of continuous output current over a wide input-supply range with excellent load and line regulation. At light loads, the regulator operates in low frequency to maintain high efficiency and low output ripple. Current mode control provides tight load transient response. RY8601 achieves low EMI signature with well-controlled switching edges. Fault condition protection includes over-voltage protection, over-current protection, short-circuit protection, thermal shutdown and input under voltage lockout. The RY8601 is available in SOT23-6 package, which provides a compact solution with minimal external components.

## **RY8601 Typical Application Circuit**

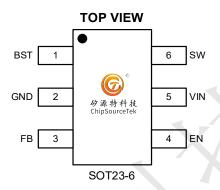


Typical Application Circuit



## **RY8601 Package and Pin Description**

### **Pin Configuration**



Top Marking: Hc<u>YLL</u> (device code: Hc, Y=year code, LL= lot number code)

### **Pin Description**

Pin	Name	Function
1	BST	Bootstrap. Requires a capacitor to drive the power switch's gate above the supply voltage. Connect this capacitor between SW and BST pins to form a floating supply across the power switch driver. An on-chip regulator charges up the bootstrap capacitor. If the on-chip regulator is not strong enough, one optional diode can be connected from VIN or VOUT to charge the external boot-strap capacitor.
2	GND	Ground Pin.
3	FB	Feedback Input. Connect a resistor divider to FB.
4	EN	Enable Input. Pull this pin below the specified threshold to shut the chip down. Pull it above the specified threshold enables the chip.
5	VIN	Input Supply Pin.
6	SW	Power Switch Output. SW is the drain of the internal MOSFET switch. Connect the power inductor and output rectifier to SW.

## RY8601 Order Information (1)

Marking	Part No.	Model	Description	Package	T/R Qty
He <u>YLL</u>	70301740	RY8601AT6	RY8601AT6 PSM Async Buck, 4.5-60V, 0.6A, 500KHz, VFB 0.8V, SOT23-6		3000PCS

Note (1): All RYCHIP parts are Pb-Free and adhere to the RoHS directive.



## **RY8601 Specifications**

### Absolute Maximum Ratings (1) (2)

Item	Min	Max	Unit
V <sub>IN</sub> voltage	-0.3	65	V
EN voltage	-0.3	65	V
SW voltage	-0.3	V <sub>IN</sub> +1V	V
SW voltage (10ns transient)	-5	V <sub>IN</sub> +2V	V
BS voltage	-0.3	Vsw+5V	V
FB voltage	-0.3	6	V
Power dissipation (3)	Internally Limited		
Operating junction temperature, T <sub>J</sub>	-40	150	°C
Storage temperature, T <sub>stg</sub>	-55	150	°C
Lead Temperature (Soldering, 10sec.)	X-3/\	260	°C

Note (1): Exceeding these ratings may damage the device.

Note (2): The device is not guaranteed to function outside of its operating conditions.

Note (3): The maximum allowable power dissipation is a function of the maximum junction temperature,  $T_{J(MAX)}$ , the junction-to-ambient thermal resistance,  $R_{\theta JA}$ , and the ambient temperature,  $T_A$ . The maximum allowable power dissipation at any ambient temperature is calculated using:  $P_{D(MAX)} = (T_{J(MAX)} - T_A)/R_{\theta JA}$ . Exceeding the maximum allowable power dissipation causes excessive die temperature, and the regulator goes into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at  $T_J = 160$ °C (typical) and disengages at  $T_J = 130$ °C (typical).

### **ESD Ratings**

Item	Description	Value	Unit
	Human Body Model (HBM)		
V <sub>(ESD-HBM)</sub>	ANSI/ESDA/JEDEC JS-001-2014	±2000	V
	Classification, Class: 2		
	Charged Device Mode (CDM)		
$V_{(ESD-CDM)}$	ANSI/ESDA/JEDEC JS-002-2014	±200	V
	Classification, Class: C0b		
	JEDEC STANDARD NO.78E APRIL 2016		
I <sub>LATCH-UP</sub>	Temperature Classification,	±150	mA
	Class: I		

### **Recommended Operating Conditions**

Item	Min	Max	Unit
Operating junction temperature (1)	-40	125	°C
Operating temperature range	-40	85	°C
Input voltage V <sub>IN</sub>	4.5	60	V
Output voltage V <sub>OUT</sub>	1	48	V
Output current	0	0.6	A

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Note (1): All limits specified at room temperature ( $T_A = 25^{\circ}$ C) unless otherwise specified. All room temperature limits are 100% production tested. All limits at temperature extremes are ensured through correlation using standard Statistical Quality Control (SQC) methods. All limits are used to calculate Average Outgoing Quality Level (AOQL).

#### **Thermal Information**

Item	Description	Value	Unit
$R_{ heta JA}$	Junction-to-ambient thermal resistance (1)(2)	105	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	55	°C/W
$R_{ heta JB}$	Junction-to-board thermal resistance	17.5	°C/W
ψлт	Junction-to-top characterization parameter	3.5	°C/W
ψյв	Junction-to-board characterization parameter	17.5	°C/W

Note (1): The package thermal impedance is calculated in accordance to JESD 51-7.

Note (2): Thermal Resistances were simulated on a 4-layer, JEDEC board

## RY8601 Electrical Characteristics (1) (2)

T<sub>A</sub>=25°C, unless otherwise specified.

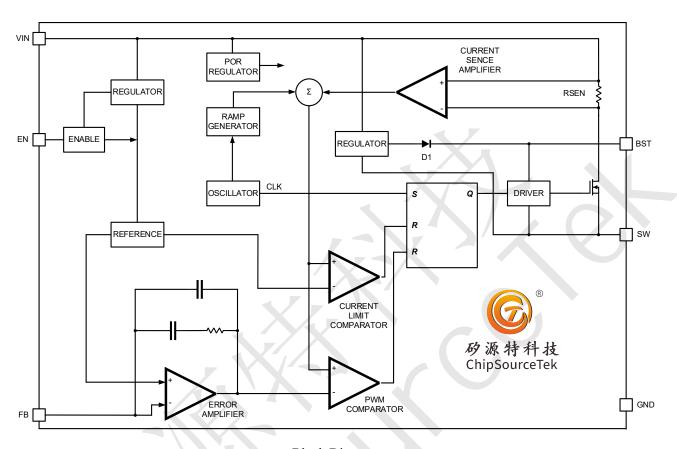
Parameter	<b>Test Conditions</b>	Min	Тур.	Max	Unit
Input Voltage Range		4.5		60	V
Supply Current (Quiescent)	$V_{EN} = 3.0V$		0.6	0.8	mA
Supply Current (Shutdown)	$V_{EN} = 0$ or $EN = GND$			4	uA
Feedback Voltage		0.780	0.800	0.820	V
Switch-On Resistance	I <sub>SW</sub> =100mA		500		$m\Omega$
Upper Switch Current Limit		1			A
Over Voltage Protection Threshold			62		V
Switching Frequency			500		KHz
Maximum Duty Cycle	VFB=90%		80		%
Minimum On-Time			100		nS
EN Rising Threshold		1.4			V
EN Falling Threshold				0.8	V
	Wake up V <sub>IN</sub> Voltage		4.2	4.5	V
Under-Voltage Lockout Threshold	Shutdown V <sub>IN</sub> Voltage	3.5	3.8		V
	Hysteresis V <sub>IN</sub> voltage		400		mV
Soft Start			1		mS
Thermal Shutdown			150		°C
Thermal Hysteresis			30		°C

Note (1): MOSFET on-resistance specifications are guaranteed by correlation to wafer level measurements.

Note (2): Thermal shutdown specifications are guaranteed by correlation to the design and characteristics analysis.



## **RY8601 Functional Block Diagram**



Block Diagram

## **RY8601 Functions Description**

#### **Internal Regulator**

The RY8601 is a current mode step down DC/DC converter that provides excellent transient response with no extra external compensation components. This device contains an internal, low resistance, high voltage power MOSFET, and operates at a 500KHz operating frequency to ensure a compact, high efficiency design with excellent AC and DC performance.

### **Under-Voltage Lockout (UVLO)**

Under-voltage lockout (UVLO) protects the chip from operating at an insufficient supply voltage. UVLO protection monitors the internal regulator voltage. When the voltage is lower than UVLO threshold voltage, the device is shut off. When the voltage is higher than UVLO threshold voltage, the device is enabled again.

### Startup and Shutdown

If both  $V_{IN}$  and EN are higher than their appropriate thresholds, the chip starts. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries. Three events can shut down the chip: EN low,  $V_{IN}$  low and thermal shutdown. In the shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The comp



voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.

#### **Current Mode Control**

The RY8601 adjusts the output voltage through the current control mode, obtains the input signal from FB, amplifies it through the internal error amplifier, and compares it with the voltage drop across the resistor through the current of the inductor. Use this to control the internal driver to control the switching of the MOSFET.

#### **PSM Mode**

The RY8601 operates in PSM mode at light load. In PSM mode, switch frequency decreases when load current drops to boost power efficiency at light load by reducing switch-loss, while switch frequency increases when load current rises, minimizing output voltage ripples.

#### **Internal Soft-Start**

The soft-start is implemented to prevent the converter output voltage from overshooting during startup. When the chip starts, the internal circuitry generates a soft-start voltage (SS) ramping up from 0V to 0.8V. When it is lower than the internal reference (REF), SS overrides REF so the error amplifier uses SS as the reference. When SS is higher than REF, REF regains control. Typical soft-start time is 1.0ms.

#### **Over Current Protection**

The RY8601 has cycle-by-cycle over current limit when the inductor current peak value exceeds the set current limit threshold. Meanwhile, output voltage starts to drop until FB is below the Under-Voltage (UV) threshold. When the output is shorted to the ground, the switching frequency is folded back and the current limit is reduced to lower the short circuit current. The frequency foldback helps prevent inductor current runaway and thermal issue during short circuit. The RY8601 exits the foldback mode once the over current condition is removed.

#### Thermal Shutdown

Thermal shutdown prevents the chip from operating at exceedingly high temperatures. When the silicon die temperature exceeds 150°C, it shuts down the whole chip. When the temperature falls below its lower threshold (Typ. 130°C) the chip is enabled again.



### **RY8601 Applications Information**

### **Setting the Output Voltage**

RY8601 require an input capacitor, an output capacitor and an inductor. These components are critical to the performance of the device. RY8601 integrates internal loop compensating resistors, so we do not recommend using a value of more than 50K for R<sub>2</sub>. The output voltage can be programmed by resistor divider.

$$V_{OUT} = V_{FB} \times \frac{R1 + R2}{R2}$$

V <sub>OUT</sub> (V)	R1(KΩ)	<b>R2</b> (ΚΩ)	L1(µH)	C1(nF)	C <sub>IN</sub> (µF)	C <sub>OUT</sub> (µF)	C <sub>FF</sub> (pF) Opt.
3.3	31.25	10	6.8	100	22	22×2	C <sub>FF</sub> Chapter
5	52.50	10	6.8	100	22	22×2	C <sub>FF</sub> Chapter
12	140.00	10	6.8	100	22	22×2	C <sub>FF</sub> Chapter
24	290.00	10	6.8	100	22	22×2	C <sub>FF</sub> Chapter
36	440.00	10	6.8	100	22	22×2	C <sub>FF</sub> Chapter
48	590.00	10	6.8	100	22	22×2	C <sub>FF</sub> Chapter

All the external components are the suggested values, the final values are based on the application testing results.

### Selecting the Inductor

The recommended inductor values are shown in the Application Diagram. It is important to guarantee the inductor core does not saturate during any foreseeable operational situation. The inductor should be rated to handle the maximum inductor peak current: Care should be taken when reviewing the different saturation current ratings that are specified by different manufacturers. Saturation current ratings are typically specified at 25°C, so ratings at maximum ambient temperature of the application should be requested from the manufacturer. The inductor value can be calculated with:

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_L \times F_{OSC}}$$

Where  $\Delta I_L$  is the inductor ripple current. Choose inductor ripple current to be approximately 30% to 40% of the maximum load current. The maximum inductor peak current can be estimated as:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Under light load conditions below 100mA, larger inductance is recommended for improved efficiency. Larger inductances lead to smaller ripple currents and voltages, but they also have larger physical dimensions, lower saturation currents and higher linear impedance. Therefore, the choice of inductance should be compromised according to the specific application.



### **Selecting the Input Capacitor**

The input current to the step-down converter is discontinuous and therefore requires a capacitor to supply AC current to the step-down converter while maintaining the DC input voltage. For a better performance, use ceramic capacitors placed as close to VIN as possible and a  $0.1\mu F$  input capacitor to filter out high frequency interference is recommended. Capacitors with X5R and X7R ceramic dielectrics are recommended because they are stable with temperature fluctuations.

The capacitors must also have a ripple current rating greater than the maximum input ripple current of the converter. The input ripple current can be estimated with Equation:

$$I_{CIN} = I_{OUT} \times \sqrt{\frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}$$

From the above equation, it can be concluded that the input ripple current reaches its maximum at  $V_{IN}=2V_{OUT}$  where  $I_{CIN}=\frac{I_{OUT}}{2}$ . For simplification, choose an input capacitor with an RMS current rating greater than half of the maximum load current.

The input capacitance value determines the input voltage ripple of the converter. If there is an input voltage ripple requirement in the system, choose the input capacitor that meets the specification. The input voltage ripple can be estimate with Equation:

$$\Delta V_{IN} = \frac{I_{OUT}}{F_{OSC} \times C_{IN}} \times \frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

Similarly, when  $V_{IN}=2V_{OUT}$ , input voltage ripple reaches its maximum of  $\Delta V_{IN}=\frac{1}{4}\times\frac{I_{OUT}}{F_{OSC}\times C_{IN}}$ .

### **Selecting the Output Capacitor**

An output capacitor is required to maintain the DC output voltage. The output voltage ripple can be estimated with Equation:

$$\Delta V_{OUT} = \frac{V_{OUT}}{F_{OSC} \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times \left(R_{ESR} + \frac{1}{8 \times F_{OSC} \times C_{OUT}}\right)$$

There are some differences between different types of capacitors. In the case of ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is mainly caused by the capacitance. For simplification, the output voltage ripple can be estimated with Equation:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times F_{OSC}^2 \times L \times C_{OUT}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

A larger output capacitor can achieve a better load transient response, but the maximum output capacitor limitation should also be considered in the design application. If the output capacitor value is too high, the output voltage will not be able to reach the design value during the soft-start time and will fail to regulate. The maximum output capacitor value ( $C_{OUT\ MAX}$ ) can be limited approximately with Equation:

$$C_{OUT\_MAX} = (I_{LIM\_AVG} - I_{OUT}) \times T_{SS} / V_{OUT}$$



Where  $L_{LIM\_AVG}$  is the average start-up current during the soft-start period, and  $T_{SS}$  is the soft- start time.

On the other hand, special attention should be paid when selecting these components. The DC bias of these capacitors can result in a capacitance value that falls below the minimum value given in the recommended capacitor specifications table.

The ceramic capacitor's actual capacitance can vary with temperature. The capacitor type X7R, which operates over a temperature range of  $-55^{\circ}$ C to  $+125^{\circ}$ C, will only vary the capacitance to within  $\pm15\%$ . The capacitor type X5R has a similar tolerance over a reduced temperature range of  $-55^{\circ}$ C to  $+85^{\circ}$ C. Many large value ceramic capacitors, larger than 1uF are manufactured with Z5U or Y5V temperature characteristics. Their capacitance can drop by more than 50% as the temperature varies from 25°C to 85°C. Therefore, X5R or X7R is recommended over Z5U and Y5V in applications where the ambient temperature will change significantly above or below 25°C.

### Feed-Forward Capacitor (C<sub>FF</sub>)

RY8601 has internal loop compensation, so adding C<sub>FF</sub> is optional. Specifically, for specific applications, if necessary, consider whether to add feed-forward capacitors according to the situation.

The use of a feed-forward capacitor ( $C_{FF}$ ) in the feedback network is to improve the transient response or higher phase margin. For optimizing the feed-forward capacitor, knowing the cross frequency is the first thing. The cross frequency (or the converter bandwidth) can be determined by using a network analyzer. When getting the cross frequency with no feed-forward capacitor identified, the value of feed-forward capacitor ( $C_{FF}$ ) can be calculated with the following Equation:

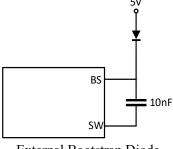
$$C_{FF} = \frac{1}{2\pi \times F_{CROSS}} \times \sqrt{\frac{1}{R1} \times \left(\frac{1}{R1} + \frac{1}{R2}\right)}$$

Where  $F_{CROSS}$  is the cross frequency.

To reduce transient ripple, the feed-forward capacitor value can be increased to push the cross frequency to higher region. Although this can improve transient response, it also decreases phase margin and cause more ringing. In the other hand, if more phase margin is desired, the feed-forward capacitor value can be decreased to push the cross frequency to lower region.

#### **External Bootstrap Diode**

Add an external bootstrap diode when the system has a fixed 5V input or when the power supply generates a 5V output. This helps improve the efficiency of the regulator. The bootstrap diode can be a low-cost one. This diode is also recommended for high-duty– cycle operation (when  $\frac{V_{OUT}}{V_{IN}} > 65\%$ ) and high output voltage (V<sub>OUT</sub>>12V) applications.



External Bootstrap Diode



## **PC Board Layout Consideration**

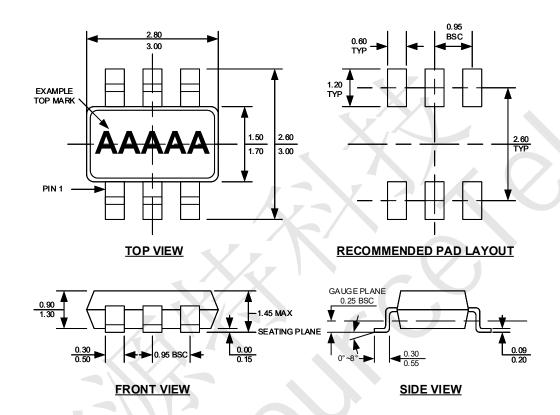
PCB layout is very important to achieve stable operation. It is highly recommended to duplicate EVB layout for optimum performance. If change is necessary, please follow these guidelines for reference.

- 1. Keep the path of switching current short and minimize the loop area formed by Input capacitor, high-side MOSFET and low-side MOSFET.
- 2. Bypass ceramic capacitors are suggested to be put close to the VIN Pin.
- 3. Ensure all feedback connections are short and direct. Place the feedback resistors and compensation components as close to the chip as possible.
- 4. VOUT, SW away from sensitive analog areas such as FB.
- 5. Connect IN, SW, and especially GND respectively to a large copper area to cool the chip to improve thermal performance and long-term reliability.



## **RY8601 Package Description**

#### SOT23-6



- 1. CONTROL DIMENSION IS IN INCHES. DIMENSION IN BRACKET IS IN MILLIMETERS.
- PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
   PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS.
- 4. LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.004" INCHES MAX.
  5. DRAWING CONFORMS TO JEDEC MS-012, VARIATION BA.
- 6. DRAWING IS NOT TO SCALE